

3 Installation and commissioning

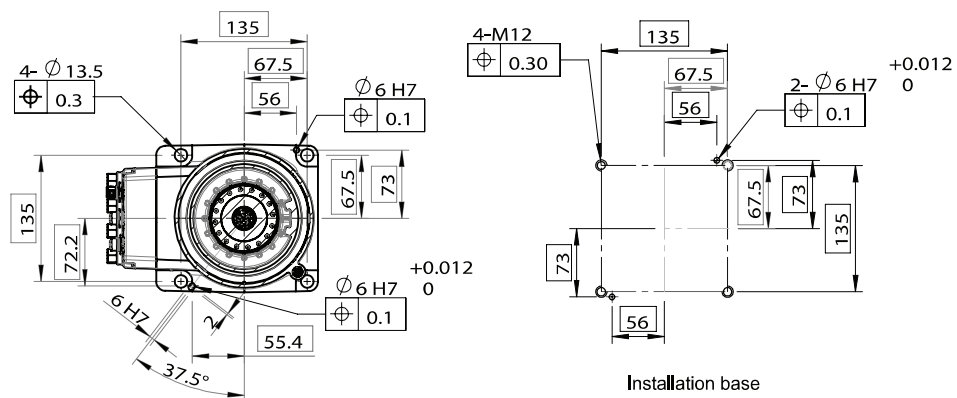
3.3.2 Orienting and securing the robot

Continued

	Action	Note
9	Tighten the bolts in a crosswise pattern to ensure that the base is not distorted.	Tightening torque: 50 Nm±5 Nm

Hole configuration, base

This illustration shows the hole configuration used when securing the robot.



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