

1 Description

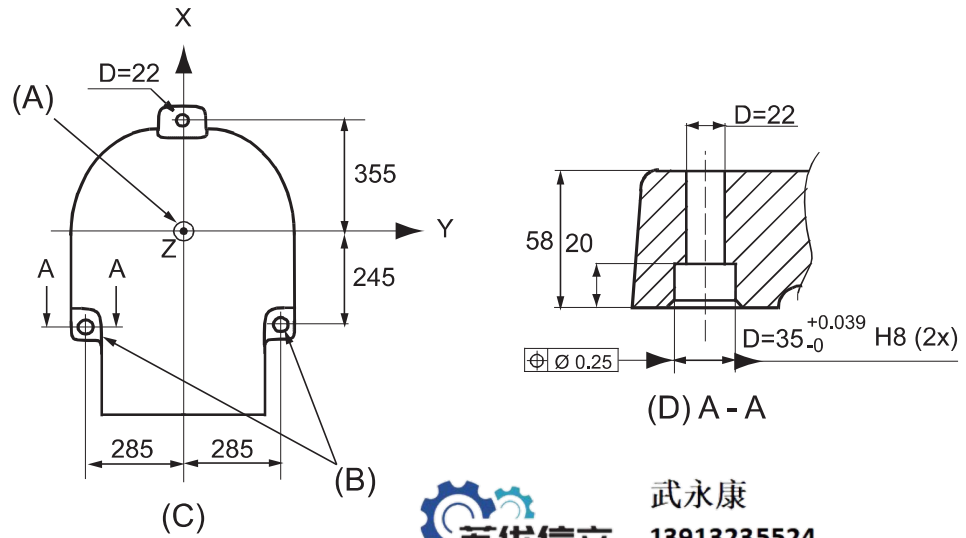
1.3.3 Mounting the manipulator

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Note regarding M_{xy} and F_{xy}

The bending torque (M_{xy}) can occur in any direction in the XY-plane of the base coordinate system. The same applies to the transverse force (F_{xy}).

Fastening holes robot base



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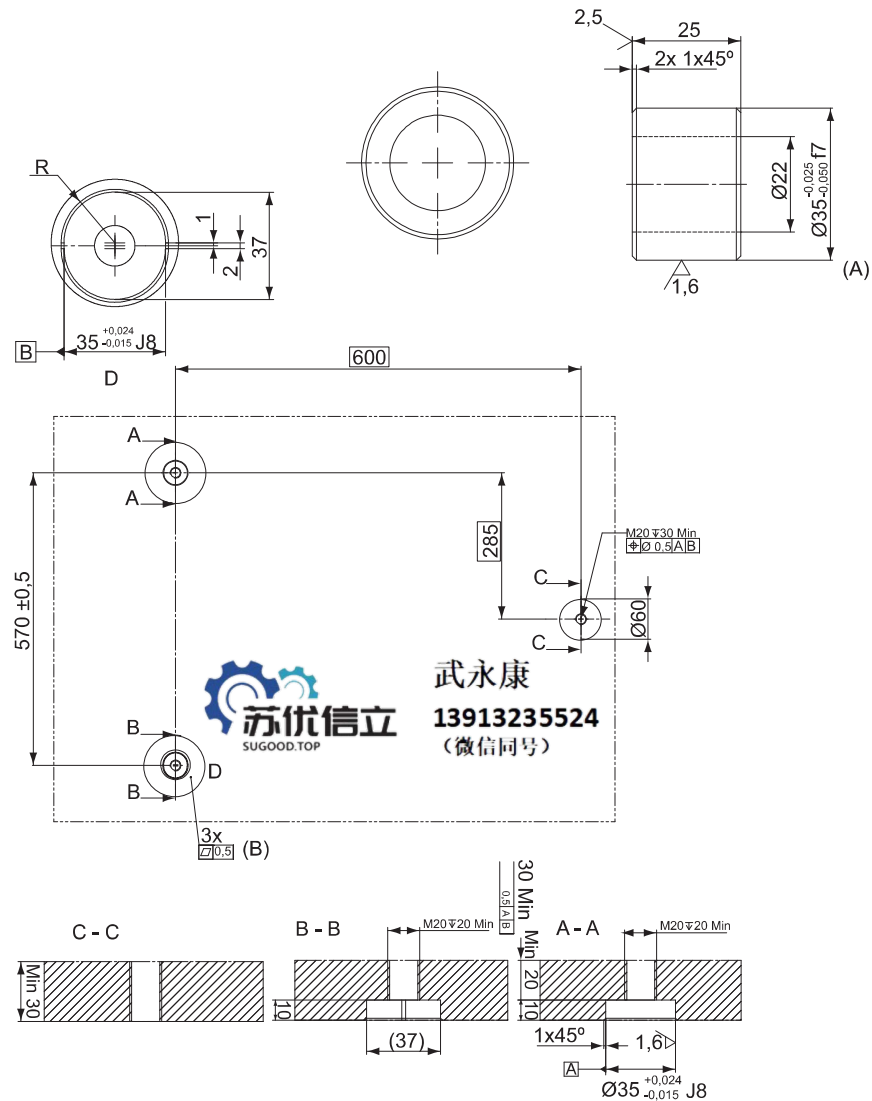


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Pos	Description
A	Z= center line
B	The same dimensions
C	View from bottom of the base
D	Section

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Mounting surface and bushings



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Pos	Description
A	Surface treatment, ISO 2081 Fe/Zn 8 c2 Guide bushings
B	Common zone